

**AIAA 2002-3140**

**Probabilistic Methods for Uncertainty  
Propagation Applied to Aircraft Design**

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# Introduction

## FLOPS Code

- Widely distributed multidisciplinary computer program
- Aircraft analysis and conceptual / preliminary design
- Weights, aerodynamics, engine cycle, propulsion data scaling / interpolation, mission performance, takeoff / landing, noise footprint, and cost analyses + program control
- Analysis, parametric variation, optimization, and contour plotting

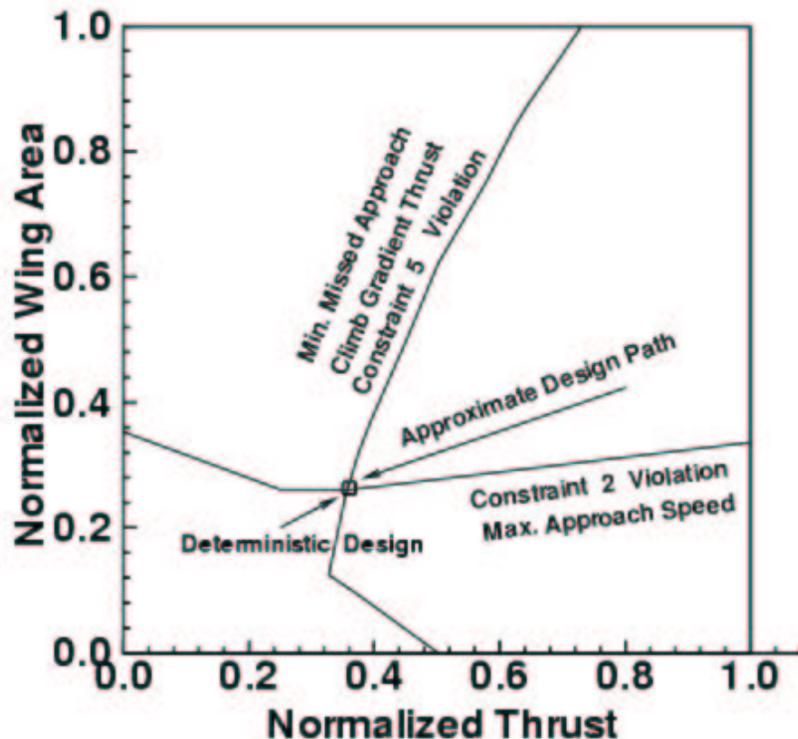
# Introduction

## FLOPS Code (Concluded)

- Major code inputs: configuration, mission performance, and noise abatement design variables, plus externally-generated engine deck and aerodynamic drag data
- Major code outputs:
  - Analysis: performance, noise, weight, and cost metrics
  - Optimization: above + design objective and constraints
- Composite objective includes a highly nonlinear constraint violation penalty function
- Constraints = range, approach speed, takeoff & landing distances, approximate missed-approach and second-segment climb gradients
- Analysis module frequently fails to produce answer

# Introduction

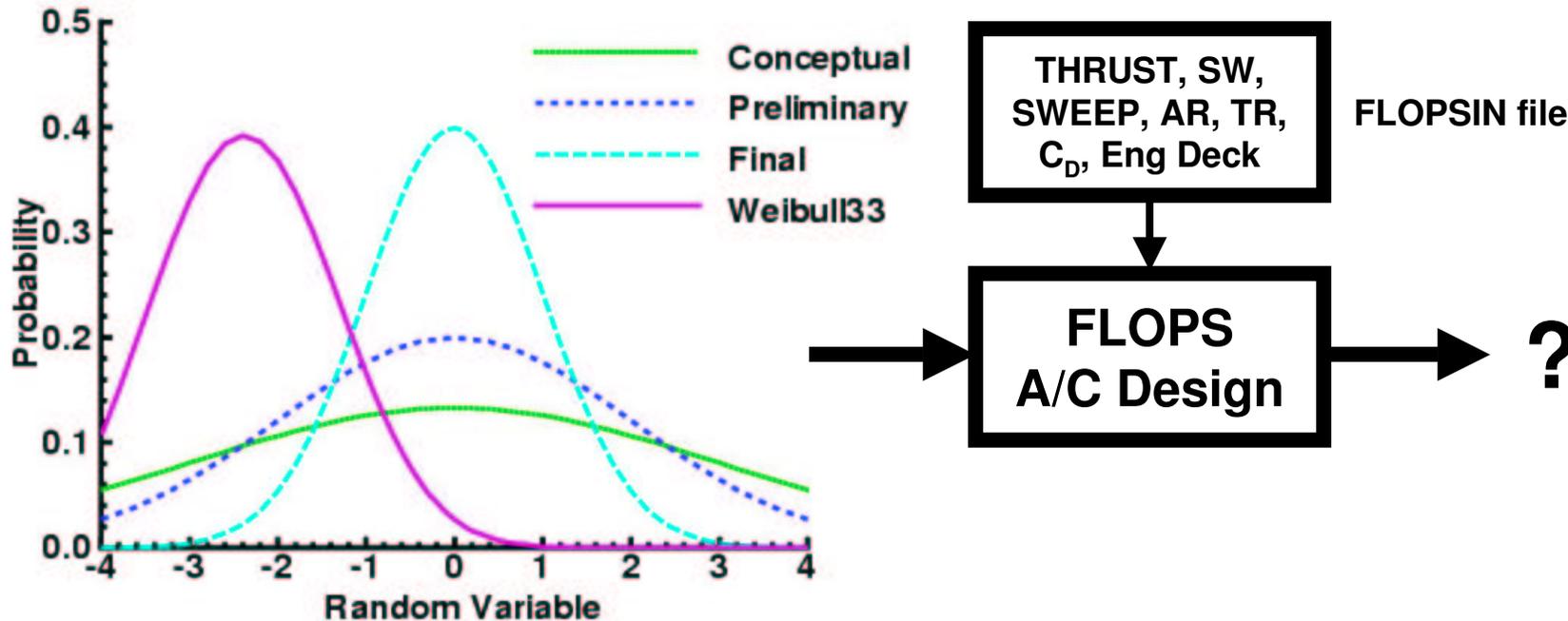
## FLOPS Subsonic Transport Design



- All inputs assumed to be precisely known (**deterministic**)
- Start from 5 design variable subsonic transport example case (xflp2.in)
- Modify input file so only THRUST (max thrust per engine) and SW (wing reference area) are active design variables
- Minimize aircraft takeoff weight with a fixed range
- Default BFGS optimization scheme
- Design path mostly in feasible region of design space
- Deterministic design lies at intersection of active constraints

# Introduction

## FLOPS Robust Design



- Characterize uncertainty (conceptual design = more uncertainty)
- Choose random variables (THRUST, SW); assess correlation
- Assign probability distribution function (PDF) type (**normal**, Weibull, etc.)
- Propagate input uncertainty through the process (FLOPS)
- Assess uncertainty in the output variables (**Obj**, Constraints, Weight, Cost, Noise)

# Introduction

## Uncertainty Methods

- Evaluate multidimensional probability density function (PDF) integral; determine associated cumulative density function (CDF)
  - Integrand not known in closed form
  - Limit state surface not known in closed form
- Uncertainty propagation methods approximate the integral evaluation
  - Method of moments – code modification  
uncertainty corrections
  - Monte Carlo simulation – code interaction with  
external software - define  
random input values
  - Commercial tools – code interaction with  
external software  
**UNIPASS**, ProFES, NESSUS

# Methodology

## Method of Moments Uncertainty Corrections

$$\textit{Traditional} : \text{Obj}_{\text{uncertain}}^2 = \overline{\text{Obj}_{\text{deterministic}}^2} + \sigma_{\text{Obj}}^2$$

$$g_{\text{uncertain}} = \overline{g_{\text{deterministic}}} + K\sigma_g$$

$$\textit{FLOPS} : \text{Obj}_{\text{uncertain}} = \sqrt{\overline{\text{Obj}_{\text{deterministic}}^2} + \sigma_{\text{Obj}}^2}$$

$$g_{\text{uncertain}, m} = \overline{g_{\text{deterministic}, m}} + K\sigma_{g_m}, \quad m = 1, 7$$

$$\textit{where} : \sigma_{\text{Obj}}^2 = \sum_{i=1}^n \left( \frac{\partial \text{Obj}}{\partial b_i} \sigma_{b_i} \right)^2, \quad \sigma_{b_i} = \overline{b_i} * \textit{c.o.v.}_i$$

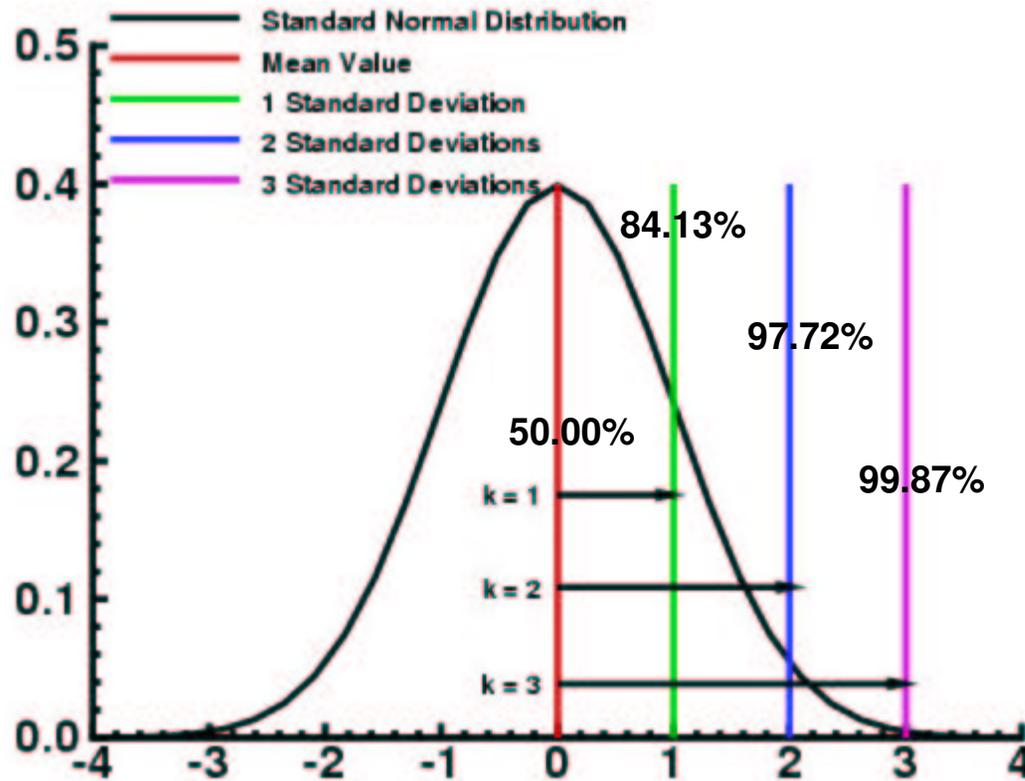
$$\textit{and} : \sigma_{g_m} = \sqrt{\sum_{i=1}^n \left( \frac{\partial g_m}{\partial b_i} \sigma_{b_i} \right)^2}, \quad m = 1, 7$$

*c.o.v.* = coefficient of variation

Derivatives constructed using Adifor  
Automatic Differentiation tool applied to FLOPS code;  
evaluated at mean values of random variables

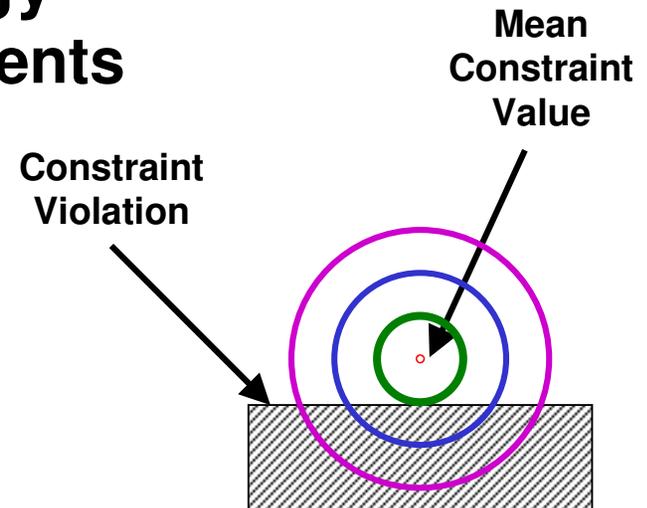
# Methodology

## Method of Moments

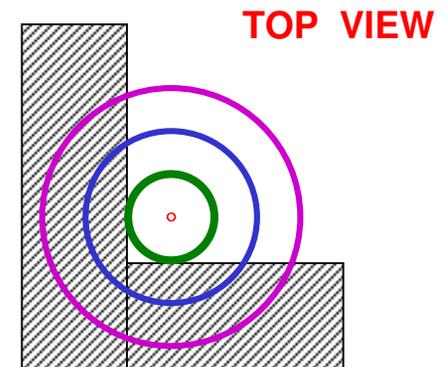


**SIDE VIEW**

Constraint mean value set back from constraint boundary for various K



1 Active Constraint  
K = 1, 84.13% Constraint Satisfaction Probability



2 Active Orthogonal Constraints  
K = 1, ~76.20% Constraint Satisfaction Probability

# Methodology

## UNIPASS version 4.2 Tool from PredictionProbe, Inc.

- Many uncertainty modeling / propagation capabilities
- Capabilities used in this study include:
  - Interface to external code
  - Model uncertainties
  - Identify most probable point (MPP) via a computationally efficient non-gradient MPP simulation search method (SSM) for discontinuous design space
  - Compute reliability index ( $\beta$ ) sensitivity data

# Methodology

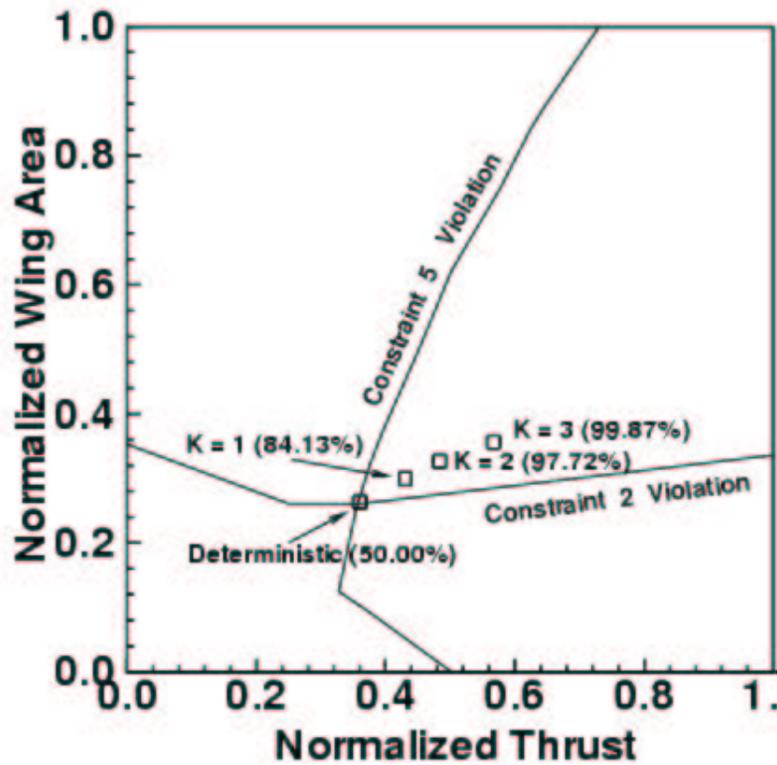
## FLOPS Uncertainty Propagation Demonstrations

- Test cases:
  - Subsonic transport aircraft design (xflp2.in)
    - Method of moments and Monte Carlo simulation
    - UNIPASS / SSM
  - Supersonic transport aircraft design (xflp3.in)
    - Method of moments / Monte Carlo simulation
    - THRUST and SW active / uncertain design variables
- Input variable uncertainty:
  - Subsonic transport aircraft design (c.o.v = 5% and 10%)
  - Supersonic transport aircraft design (c.o.v = 0.05% and 0.08%)
  - Assume normal distributions and uncorrelated variables

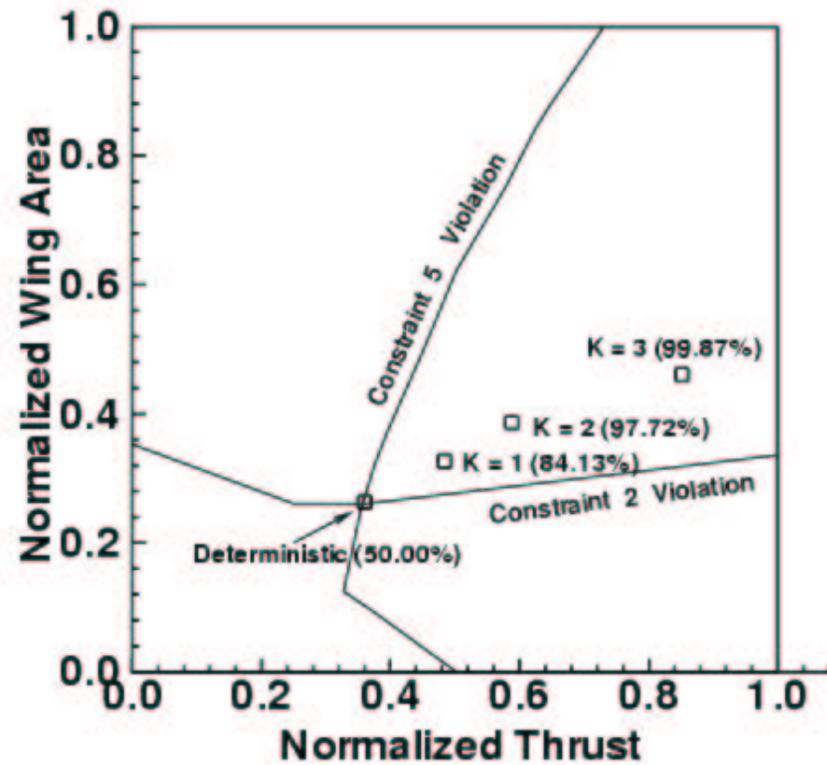
# Method of Moments Results

## Subsonic Transport

### Deterministic and Robust Designs



c.o.v. = 5%

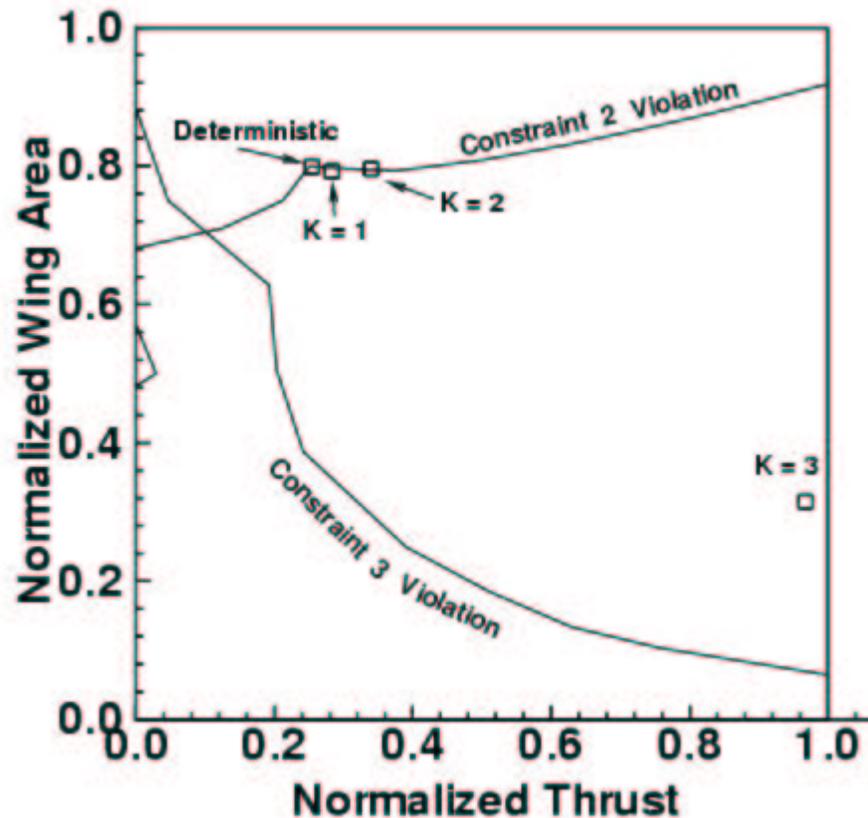


c.o.v. = 10%

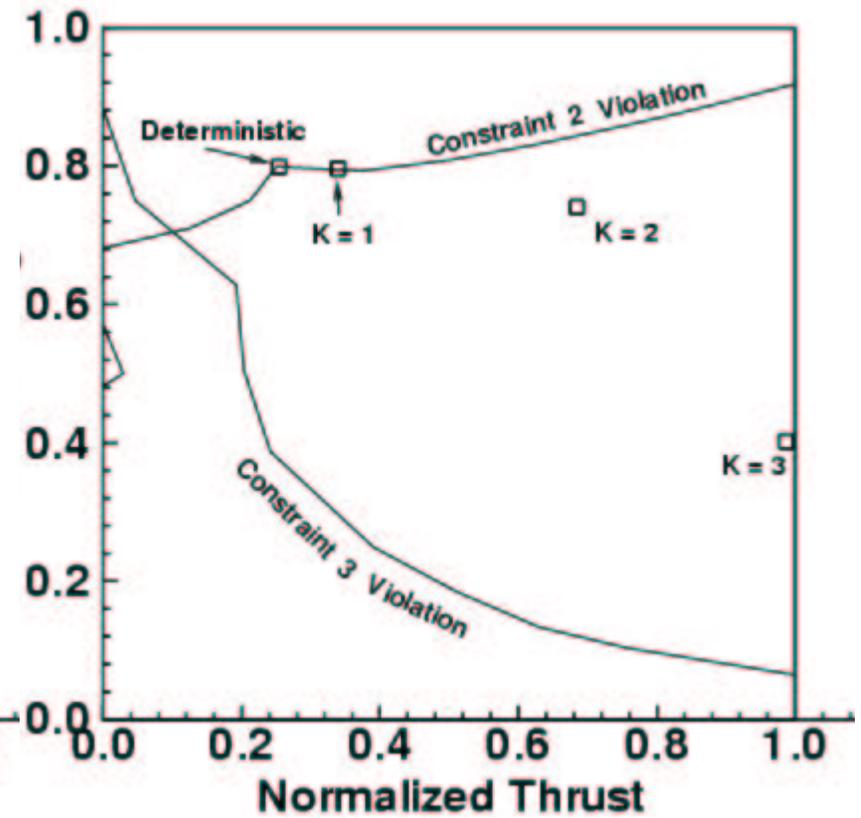
# Method of Moments Results

## Supersonic Transport

### Deterministic and Robust Designs



c.o.v. = 0.05%

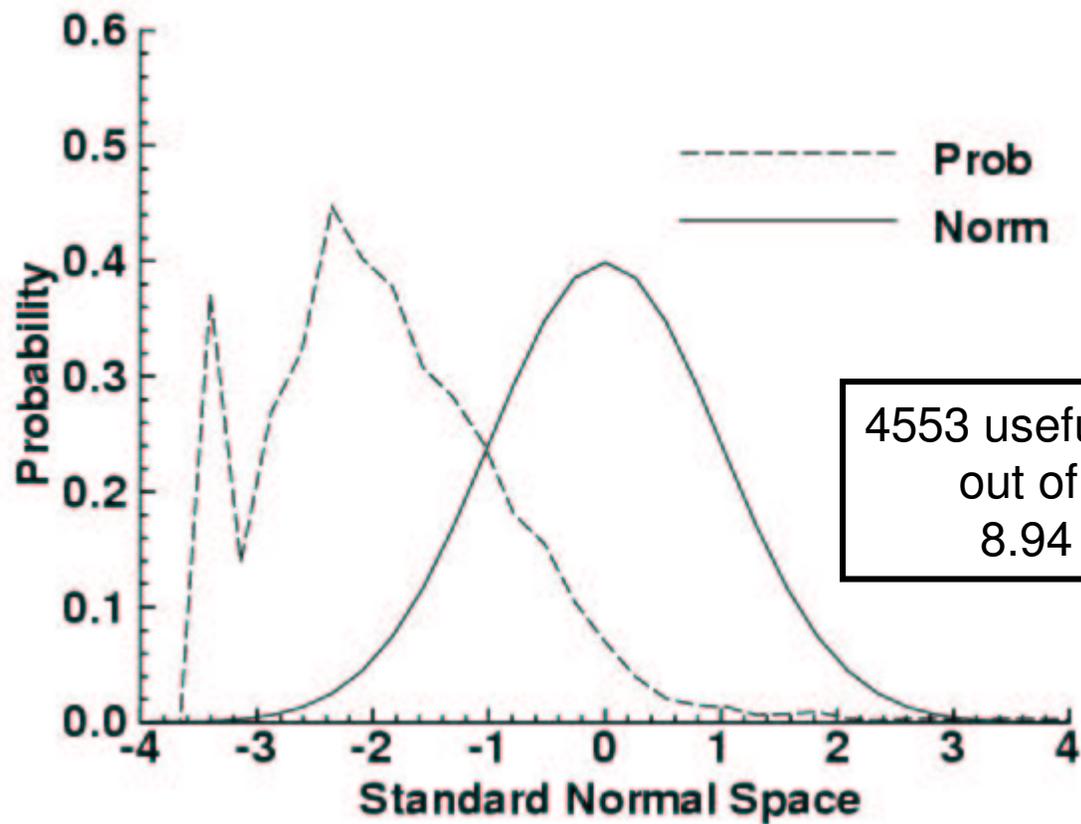


c.o.v. = 0.08%

# Monte Carlo Simulation Results

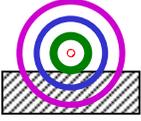
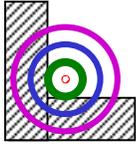
## Supersonic Transport

### Deterministic Design Point



# Monte Carlo Simulation Results

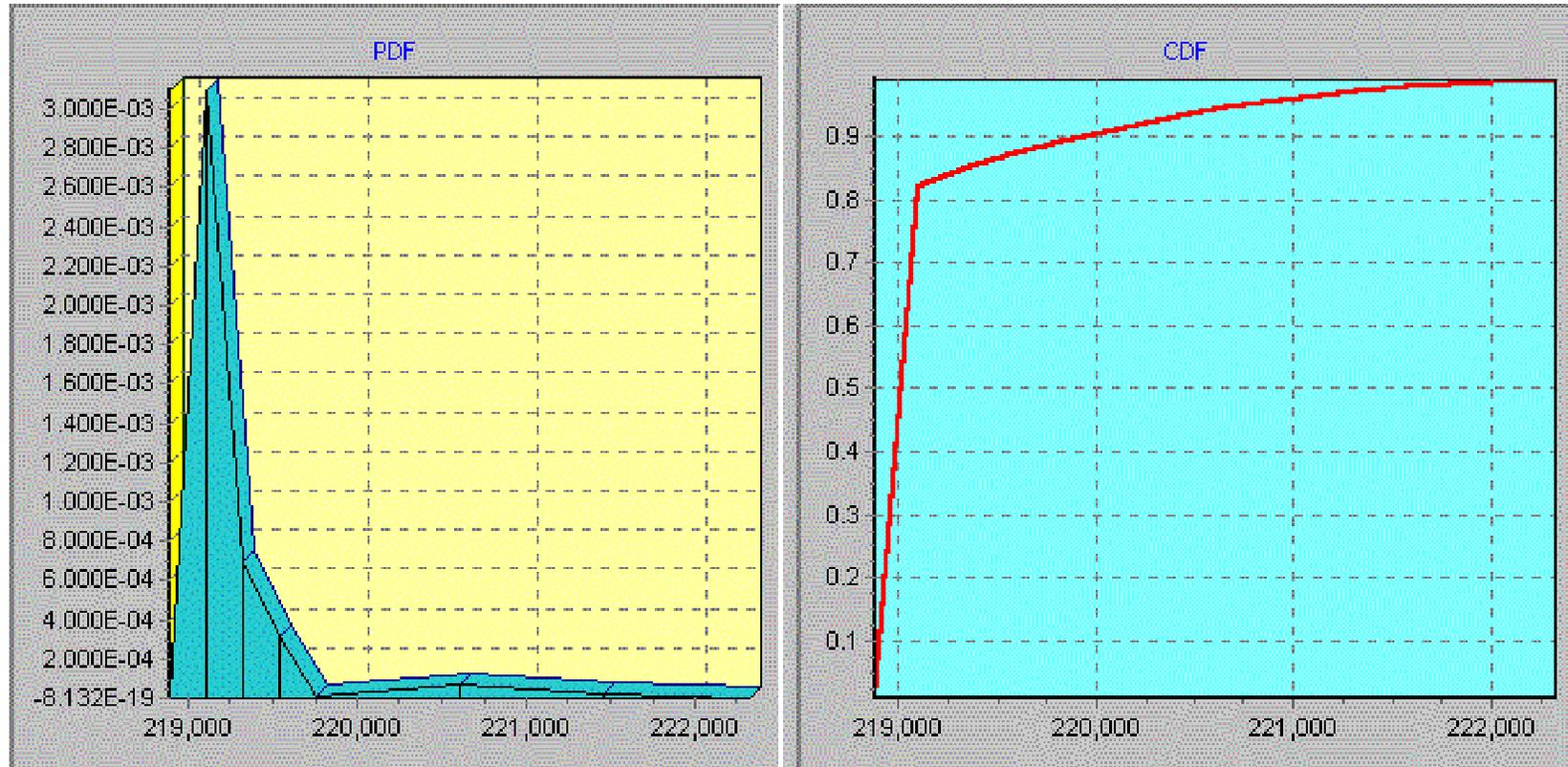
## Constraint Satisfaction Probability

Problem	Case	Constraint Satisfaction Probability (%)		
				Monte Carlo Simulation
Subsonic	Deterministic	50	~25	~30
Subsonic	K = 1	84	~76	~80
Subsonic	K = 2	98	~97	~90
Subsonic	K = 3	100	~100	~100
Supersonic	Deterministic	50	~25	~20
Supersonic	K = 1	84	~76	~30
Supersonic	K = 2	98	~97	~70
Supersonic	K = 3	100	~100	too close to DV bounds

Experimentally determined constraint satisfaction probabilities using Monte Carlo simulation with c.o.v. = 10% for all cases.

# UNIPASS Results

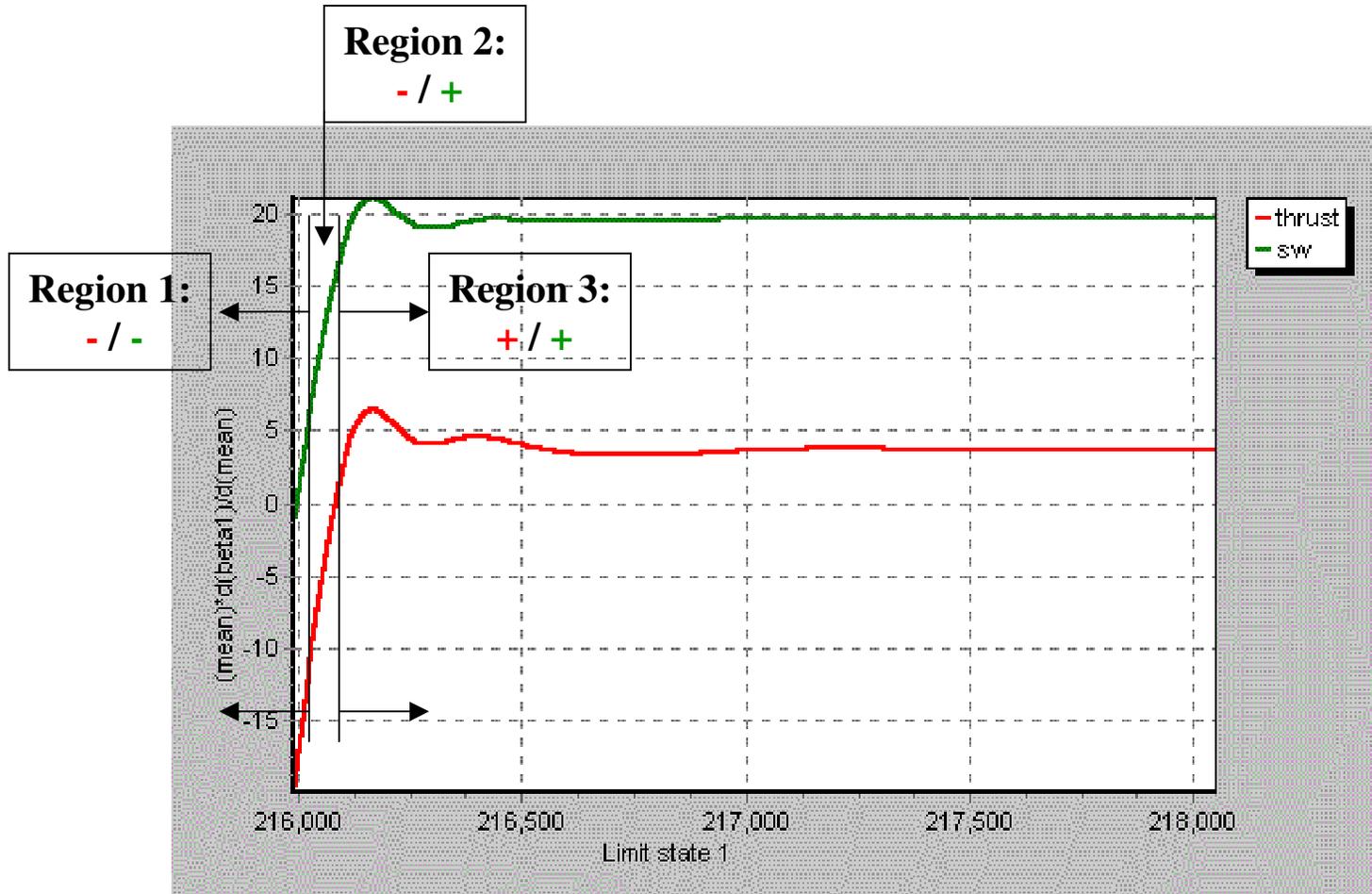
## PDF / CDF Analysis, Subsonic Transport Deterministic Design Point, c.o.v = 5%



263 useful FLOPS analyses out of 457 samples; 42.45 % failure rate  
Average FLOPS failure rate for analyses ~ 28%

# UNIPASS Results

$\beta$ -Gradient Analysis, Subsonic Transport  
Deterministic Design Point, c.o.v = 5%



Results still under investigation

# Concluding Remarks

- Initial FLOPS uncertainty propagation results
- Further research with code, methods, and test problems recommended
- Method of Moments uncertainty propagation
  - 2 example problems (subsonic / supersonic transport design)
  - 2 levels input uncertainty (c.o.v.) specified for each problem
  - 4 levels of satisfaction ( $K$ ) required for a single constraint (0,1,2,3)
- Subsonic transport design problem
  - Similar, feasible deterministic / robust design paths
  - Reasonable levels of uncertainty imposed
  - Non-normal output distribution
  - Reasonably accurate constraint failure probability prediction
- Supersonic transport design problem
  - Different, curious, and infeasible deterministic / robust design paths
  - Great sensitivity to small levels of input uncertainty
  - Skewed, bi-modal output distribution
  - Constraint failure probability under-predicted
- UNIPASS / Simulation Search Method uncertainty propagation
  - Computationally more efficient than Monte Carlo simulation
  - PDF / CDF, MPP, and  $\beta$ -gradient computations demonstrated
  - Easily implement uncertainty propagation with external software

# Methodology

## Method of Moments

Random input variables:  $B = \{b_1, \dots, b_n\}$   
 Mean values:  $\bar{B} = \{\bar{b}_1, \dots, \bar{b}_n\}$ ,  
 Standard deviations:  $\sigma_b = \{\sigma_1, \dots, \sigma_n\}$ ,  $\sigma_{b_i} = \bar{b}_i * (c.o.v.)_i$ ,  
*c.o.v. = coefficient of variation*

Taylor series: 
$$F(B) = F(\bar{B}) + \sum_{i=1}^n \frac{\partial F}{\partial b_i} (b_i - \bar{b}_i) + \frac{1}{2!} \sum_{j=1}^n \sum_{i=1}^n \frac{\partial^2 F}{\partial b_i \partial b_j} (b_i - \bar{b}_i) (b_j - \bar{b}_j)$$

Uncertainty Expressions  

$$\bar{F} = F(\bar{B}), \quad \text{FOFM} \quad \leftarrow$$

(F=First, S=Second  
 O=Order, M=Moment): 
$$\sigma_F^2 = \sum_{i=1}^n \left( \frac{\partial F}{\partial b_i} \sigma_{b_i} \right)^2, \quad \text{FOSM} \quad \leftarrow$$

$$\bar{F} = F(\bar{B}) + \frac{1}{2!} \sum_{i=1}^n \frac{\partial^2 F}{\partial b_i^2} \sigma_{b_i}^2, \quad \text{SOFM}$$

$$\sigma_F^2 = \sum_{i=1}^n \left( \frac{\partial F}{\partial b_i} \sigma_{b_i} \right)^2 + \frac{1}{2!} \sum_{j=1}^n \sum_{i=1}^n \left( \frac{\partial^2 F}{\partial b_i \partial b_j} \sigma_{b_i} \sigma_{b_j} \right)^2, \quad \text{SOSM}$$